

NAG Toolbox for MATLAB

g02gk

1 Purpose

g02gk calculates the estimates of the parameters of a generalized linear model for given constraints from the singular value decomposition results.

2 Syntax

```
[b, se, cov, ifail] = g02gk(v, c, b, s, 'ip', ip, 'iconst', iconst)
```

3 Description

g02gk computes the estimates given a set of linear constraints for a generalized linear model which is not of full rank. It is intended for use after a call to g02ga, g02gb, g02gc or g02gd.

In the case of a model not of full rank the functions use a singular value decomposition to find the parameter estimates, $\hat{\beta}_{\text{svd}}$, and their variance-covariance matrix. Details of the SVD are made available in the form of the matrix P^* :

$$P^* = \begin{pmatrix} D^{-1}P_1^T \\ P_0^T \end{pmatrix}$$

as described by g02ga, g02gb, g02gc and g02gd. Alternative solutions can be formed by imposing constraints on the parameters. If there are p parameters and the rank of the model is k then $n_c = p - k$ constraints will have to be imposed to obtain a unique solution.

Let C be a p by n_c matrix of constraints, such that

$$C^T\beta = 0,$$

then the new parameter estimates $\hat{\beta}_c$ are given by:

$$\begin{aligned} \hat{\beta}_c &= A\hat{\beta}_{\text{svd}} \\ &= \left(I - P_0(C^TP_0)^{-1} \right) \hat{\beta}_{\text{svd}}, \end{aligned} \quad \text{where } I \text{ is the identity matrix,}$$

and the variance-covariance matrix is given by

$$AP_1D^{-2}P_1^TA^T$$

provided $(C^TP_0)^{-1}$ exists.

4 References

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

McCullagh P and Nelder J A 1983 *Generalized Linear Models* Chapman and Hall

Searle S R 1971 *Linear Models* Wiley

5 Parameters

5.1 Compulsory Input Parameters

1: **v(ldv,ip + 7)** – double array

ldv, the first dimension of the array, must be at least **ip**. **ldv** should be as supplied to g02ga, g02gb, g02gc or g02gd.

The array **v** as returned by g02ga, g02gb, g02gc or g02gd.

2: **c(ldc,iconst) – double array**

ldc, the first dimension of the array, must be at least **ip**.

Contains the **iconst** constraints stored by column, i.e., the *i*th constraint is stored in the *i*th column of **c**.

3: **b(ip) – double array**

The parameter estimates computed by using the singular value decomposition, $\hat{\beta}_{\text{svd}}$.

4: **s – double scalar**

The estimate of the scale parameter.

For results from g02ga and g02gd then **s** is the scale parameter for the model, σ^2 .

For results from g02gb and g02gc then **s** should be set to 1.0.

Constraint: $s > 0.0$.

5.2 Optional Input Parameters

1: **ip – int32 scalar**

Default: The dimension of the arrays **p**, **ip**, **se**, **cov**. (An error is raised if these dimensions are not equal.)

p, the number of terms in the linear model.

Constraint: $ip \geq 1$.

2: **iconst – int32 scalar**

Default: The dimension of the array **c**.

the number of constraints to be imposed on the parameters, n_c .

Constraint: $0 < \text{iconst} < ip$.

5.3 Input Parameters Omitted from the MATLAB Interface

ldv, ldc, wk

5.4 Output Parameters

1: **b(ip) – double array**

The parameter estimates of the parameters with the constraints imposed, $\hat{\beta}_c$.

2: **se(ip) – double array**

The standard error of the parameter estimates in **b**.

3: **cov((ip × (ip + 1)/2)) – double array**

The upper triangular part of the variance-covariance matrix of the **ip** parameter estimates given in **b**. They are stored packed by column, i.e., the covariance between the parameter estimate given in **b**(*i*) and the parameter estimate given in **b**(*j*), $j \geq i$, is stored in **cov**($j \times (j - 1)/2 + i$).

4: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **ip** < 1.
 or **iconst** ≥ **ip**,
 or **iconst** ≤ 0,
 or **ldv** < **ip**,
 or **ldc** < **ip**,
 or **s** ≤ 0.0.

ifail = 2

c does not give a model of full rank.

7 Accuracy

It should be noted that due to rounding errors a parameter that should be zero when the constraints have been imposed may be returned as a value of order *machine precision*.

8 Further Comments

g02gk is intended for use in situations in which dummy (0 – –1) variables have been used such as in the analysis of designed experiments when you do not wish to change the parameters of the model to give a full rank model. The function is not intended for situations in which the relationships between the independent variables are only approximate.

9 Example

```
v = [4.890297476493481, 132.9931304975522, 0.08671323636775569,
11.53226476012202, ...
0.6875039713237874, 0.6035396163882434, 0, 0.0190106784478845,
0.008405335397184037, ...
0.008587821997748737, 0.002017521052951722, 0.006018698150011753,
...
0.002569439508216107, 0.005710268118949224, 0.003195800397035001,
0.001516472273672414;
4.150630280659896, 63.47399412403458, 0.1255168658332746,
7.96705680436851, ...
0.4385677120269487, 0.5137644803624514, 0, -0.0002104052850739208, -
0.03362644601906961, ...
0.03352834001769896, -0.0001122992837032618, -8.410523978672018e-05,
...
-1.834202533241677e-05, -7.350180559025446e-05, -2.50373181392074e-
05, -9.418896225321663e-06;
4.847173050021614, 127.3797841010689, 0.08860326907783028,
11.28626528578293, ...
-1.207211262022778, 0.5962906923855547, 0, -0.000593266263451917, -
0.0003445349204235381, ...
-0.000333175581116977, 8.444423808860036e-05, 0.04164067761137802,
...
-0.000834602710139113, -0.03974432490123243, -0.001281738894244829, -
0.0003732773692135418;
4.347583499449088, 77.29146221158076, 0.1137455037136346,
8.791556302019613, ...
0.193629026736895, 0.5316079856446033, 0, -0.005604448606553034, -
0.00473076223435367, ...
-0.004660408745794929, 0.003786722373595579, 0.03079195529372083,
...
-0.01961182893501804, 0.03434336417204345, -0.04455401443460466, -
```

```

0.006573924702694605;
      3.660007365784039,   38.86162911664574,   0.160412976990412,
6.23390961729842, ...
      0.02218333268101244, 0.4819807366090336, 0, -0.01246501079735563,
0.02562719062269757, ...
      0.02538801446619446, -0.06348021588624767, -0.003268009116713865,
...
      0.01218311975746848, -0.003443738617825787, -0.01974708083814387,
0.001810698017859427;
      4.906081344202832,   135.1089303020151,   0.08603159451608589,
11.62363670724507, ...
      -0.3553126814370362, 0.6083327470988832, 0, -0.007494797532342946,
0.006087596749368498, ...
      0.006034528387724169, -0.01961692266943561, 0.009789429893167587,
...
      -0.06230084141169696, 0.01026746382279108, 0.04102802603588968, -
0.006278875872494353;
      4.166414148369245,   64.48380766743846,   0.1245301935277972,
8.030181048235367, ...
      0.1880789664600944, 0.5196429754104227, 0, -0.007856295692343652, -
0.001520639263699578, ...
      -0.001513684000176248, -0.004821972428467818, 0.01450100243772308,
...
      0.03053649776467425, 0.01481400539841174, 0.02215701246445583, -
0.08986481375760852;
      4.862956917730965,   129.4062806673598,   0.08790676991659417,
11.37568814038781, ...
      1.174924303092439, 0.6011714612100958, 0, 0.4644148349507297, -
0.508180337140321, ...
      -0.508180337140321, -0.508180337140321, 0.04376550218959127, ...
      0.04376550218959111, 0.04376550218959127, 0.04376550218959124,
0.04376550218959125;
      4.363367367158438,   78.52109911103648,   0.1128513646061788,
8.861213185057478, ...
      -0.7464706890225739, 0.5372707561039687, 0, -0.3635174659273034, -
0.05120849696428324, ...
      -0.05120849696428324, -0.05120849696428316, 0.4147259628915867, ...
      0.4147259628915865, 0.4147259628915868, 0.4147259628915868,
0.4147259628915868];
c = [0, 0;
     1, 0;
     1, 0;
     1, 0;
     0, 1;
     0, 1;
     0, 1;
     0, 1;
     0, 1;
     0, 1];
b = [2.597657842414576;
     1.261948923584132;
     1.277732791293482;
     0.05797612753696259;
     1.030690710494773;
     0.2910235146611871;
     0.9875662840229057;
     0.4879767334503795;
     -0.1995994002146691];
s = 1;
[bOut, se, cov, ifail] = g02gk(v, c, b, s)

bOut =
  3.9831
  0.3961
  0.4118
 -0.8079
  0.5112
 -0.2285
  0.4680
 -0.0316
 -0.7191

```

```
se =
  0.0396
  0.0458
  0.0457
  0.0622
  0.0562
  0.0727
  0.0569
  0.0675
  0.0887
cov =
  0.0016
 -0.0006
  0.0021
 -0.0006
 -0.0002
  0.0021
  0.0012
 -0.0019
 -0.0019
  0.0039
 -0.0006
  0.0000
 -0.0000
  0.0000
  0.0032
  0.0002
 -0.0000
  0.0000
 -0.0000
 -0.0008
  0.0053
 -0.0005
  0.0000
 -0.0000
 -0.0000
 -0.0001
 -0.0008
  0.0032
 -0.0001
  0.0000
 -0.0000
 -0.0000
 -0.0006
 -0.0013
 -0.0006
  0.0046
  0.0010
 -0.0000
  0.0000
  0.0000
 -0.0017
 -0.0024
 -0.0017
 -0.0021
  0.0079
ifail =
      0
```